

## FIXED POINTS OF $f$ -CONTRACTIVE MAPS

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1. **Introduction.** Let  $(X, d)$  be a metric space. A fixed point of a map  $g: X \rightarrow X$  is a common fixed point of  $g$  and the identity map  $1_X$  of  $X$ . Motivated by this fact, we replace  $1_X$  by a continuous map  $f: X \rightarrow X$ , and obtain the following.

**DEFINITIONS.** Let  $f$  be a continuous self-map of  $X$ . Then a self-map  $g$  of  $X$  is said to be  $f$ -contractive if  $d(gx, gy) < d(fx, fy)$  for all  $x, y \in X$ ,  $gx \neq gy$ .

Let  $C_f$  denote the family of all maps  $g: X \rightarrow X$  such that  $gX \subset fX$  and  $gf = fg$ . Given a point  $x_0 \in X$  and a map  $g \in C_f$ , an  $f$ -iteration of  $x_0$  under  $g$  is a sequence  $\{fx_n\}_{n=1}^{\infty}$  such that  $fx_n = gx_{n-1}$ .

We observe that an  $f$ -contractive map is always continuous. Note that given  $x_0 \in X$ , its  $f$ -iteration under  $g$  is not unique; however, in case  $f = 1_X$ , these definitions reduce to the usual ones.

We give conditions under which  $f$ -contractive maps have fixed points. In fact, necessary and sufficient conditions for the existence of fixed points of continuous self-maps of  $X$  are given. In order to do this, criteria for an  $f$ -iteration to be Cauchy are of interest. In this direction, Geraghty [5] obtained important results on usual contractive maps and iterations.

In this paper, we generalize results of Edelstein [4], Rakotch [7], and Geraghty [5] on the existence of fixed points, and, consequently, obtain many extended forms of the Banach contraction principle, especially those of Boyd-Wong [2], [8], Geraghty [5], Jungck [6], and Rakotch [7].

In § 2, basic n.a.s.c.'s for the existence of fixed points of self-maps of an arbitrary metric space and their applications are given.

In § 3, we give a n.a.s.c. that an  $f$ -iteration of  $x_0 \in X$  under  $g$  be convergent. This condition is used to prove criteria for the existence of fixed points for metric spaces more general than complete ones. Some applications are also considered.

Throughout this paper,  $X$  denotes a metric space with metric  $d$ , and  $f$  denotes always a continuous self-map of  $X$ .

2. **General existence theorems.** In this section, we give some n.a.s.c.'s for the existence of fixed points of a continuous self-map  $f$  of  $X$ . First, we need the following.

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LEMMA 2.1. *Let  $f$  and  $g$  be commuting self-maps of a metric space  $X$ . If  $g^N$  is  $f$ -contractive for some integer  $N > 0$  and  $f, g^N$  have a point of coincidence  $\zeta \in X$ , then  $f\zeta$  is the unique common fixed point of  $f$  and  $g$ .*

PROOF. Let  $\eta = f\zeta = g^N\zeta$  and  $\eta \neq f\eta$ . Then  $d(\eta, f\eta) = d(g^N\zeta, g^Nf\zeta) < d(f\zeta, ff\zeta) = d(\eta, f\eta)$  leads to a contradiction. Therefore  $\eta = f\eta = g^N\eta$ . Suppose  $f$  and  $g^N$  have another common fixed point  $\eta'$ . Then  $d(\eta, \eta') = d(g^N\eta, g^N\eta') < d(f\eta, f\eta') = d(\eta, \eta')$  leads to another contradiction. Therefore  $\eta$  is the unique common fixed point of  $f$  and  $g^N$ . But from  $\eta = f\eta = g^N\eta$  we have  $g\eta = f(g\eta) = g^N(g\eta)$ , whence  $g\eta = \eta$ . Thus  $\eta$  is a common fixed point of  $f$  and  $g$ . Now,  $\eta$  is unique since  $\eta' = f\eta' = g\eta'$  implies  $\eta' = f\eta' = g^N\eta'$ .

The following is basic in this paper.

THEOREM 2.2. *A continuous self-map  $f$  of  $X$  has a fixed point iff there exists an  $f$ -contractive map  $g$  in  $C_f$  such that for some  $x_0 \in X$ , an  $f$ -iteration  $\{fx_n\}$  of  $x_0$  under  $g$  has a subsequence  $\{fx_{n_i}\}$  converging to a point  $\zeta \in X$ . Indeed,  $f$  and  $g$  have a unique common fixed point  $f\zeta$ .*

PROOF. Suppose that  $f\eta = \eta$  for some  $\eta \in X$ . Define  $g : X \rightarrow X$  by  $gx = \eta$  for all  $x \in X$ . Then clearly  $g \in C_f$  and  $g$  is  $f$ -contractive. Note that for any  $x \in X$ , its  $f$ -iteration under  $g$  converges to  $\eta$  and  $\eta$  is the unique common fixed point of  $f$  and  $g$ .

Conversely, from the continuities of  $f, g$  and  $fx_{n_i} \rightarrow \zeta$ , we have  $ffx_{n_i} \rightarrow f\zeta$  and  $gfx_{n_i} \rightarrow g\zeta$ . We define a function  $r : Y = fX \times fX - \Delta \rightarrow \mathbf{R}$  by  $r(fp, fq) = d(gp, gq)/d(fp, fq)$ , where  $\Delta$  denotes the diagonal of  $X$ . Then  $r$  is continuous and  $r(fp, fq) < 1$ . Thus if  $f\zeta \neq g\zeta$ , there is an  $\alpha$ ,  $0 < \alpha < 1$ , and an open set  $U$  of  $Y$  such that  $(f\zeta, g\zeta) \in U$  and if  $(fp, fq) \in U$  then  $0 \leq r(fp, fq) < \alpha$ . Now choose  $\rho > 0$  so that (1)  $\rho < (1/3)d(f\zeta, g\zeta)$  and (2) if  $B_1 = B(f\zeta, \rho)$  and  $B_2 = B(g\zeta, \rho)$  are open balls, then  $B_1 \times B_2 \subset U$ . Since  $ffx_{n_i} \rightarrow f\zeta$  and  $gfx_{n_i} \rightarrow g\zeta$ , there exists  $N > 0$  such that  $i > N$  implies  $ffx_{n_i} \in B_1$  and  $gfx_{n_i} \in B_2$ . Therefore  $d(ffx_{n_i}, gfx_{n_i}) > \rho$  for all  $i > N$ . On the other hand, from the definition of  $r$ , the choice of  $U$ , and the fact that  $ffx_{n_i} = gfx_{n_{i-1}}$ , we have

$$d(ffx_{n_{i+1}}, ffx_{n_{i+2}}) < \alpha d(ffx_{n_i}, ffx_{n_{i+1}}).$$

Further, if  $l > j > N$ , then

$$\begin{aligned} d(ffx_{n_j}, ffx_{n_{j+1}}) &\leq d(ffx_{n_{l-1+1}}, ffx_{n_{l-1+2}}) \\ &< \alpha d(ffx_{n_{l-1}}, ffx_{n_{l-1+1}}). \end{aligned}$$

Then by repeating this argument we get

$$d(ffx_{n_j}, ffx_{n_{j+1}}) < \alpha^{l-j} d(ffx_{n_j}, ffx_{n_{j+1}}).$$

But with fixed  $j$ ,  $\alpha^{l-j} \rightarrow 0$  as  $l \rightarrow \infty$ , whence  $d(ffx_n, ffx_{n+l}) \rightarrow 0$ . This contradicts  $d(ffx_n, gfx_n) > \rho$  for  $l > N$ . Thus we conclude that  $f\xi = g\xi$ , and, by Lemma 2.1,  $\eta = f\xi$  is the unique common fixed point of  $f$  and  $g$ .

If  $f = 1_X$ , Theorem 2.2 is reduced to a theorem of Edelstein [4].

From Lemma 2.1 and Theorem 2.2, we have

**COROLLARY 2.3.** *A continuous self-map  $f$  of a compact metric space  $X$  has a fixed point iff there exists a map  $g$  in  $C_f$  such that for some integer  $N > 0$ ,  $g^N$  is  $f$ -contractive. Indeed,  $f$  and  $g$  have a unique common fixed point.*

In case  $f = 1_X$ , Corollary 2.3 is a particular case of a result of Bailey [1], and is reduced to a result of Edelstein [4] whenever  $N = 1$ .

**THEOREM 2.4.** *A continuous self-map  $f$  of a metric space  $X$  has a fixed point iff there exists an  $f$ -contractive map  $g$  in  $C_f$ , a subset  $M \subset X$  and a point  $x_0 \in M$  such that*

$$(1) \quad d(fx, fx_0) - d(gx, gx_0) \geq 2d(fx_0, gx_0)$$

for every  $x \in X - M$  and  $g$  maps  $M$  into a compact subset of  $X$ . Indeed,  $f$  and  $g$  have a unique common fixed point.

**PROOF.** Suppose that  $f\eta = \eta$  for some  $\eta \in X$ . Define  $g : X \rightarrow X$  by  $gx = \eta$  for all  $x \in X$ . Then  $g$  is in  $C_f$  and  $f$ -contractive. Putting  $x_0 = \eta$  and  $M = \{\eta\}$ , the necessity follows.

Conversely, if  $fx_0 = gx_0$ , it is the unique common fixed point of  $f$  and  $g$ , by Lemma 2.1. Suppose  $fx_0 \neq gx_0$  and let  $\{fx_n\}_{n=1}^\infty$  be an  $f$ -iteration of  $x_0$  under  $g$ . Since  $g$  maps  $M$  into a compact set by assumption, by Theorem 2.2, it suffices to show that  $x_n \in M$  for every  $n$ . Since  $g$  is  $f$ -contractive, if  $fx_{n-1} = fx_n$ , i.e.,  $gx_{n-1} = fx_{n-1}$ , for some  $n$ , then, by Lemma 2.1,  $f$  and  $g$  already have a unique common fixed point. Hence we may assume that  $d(fx_n, fx_{n+1}) < d(fx_{n-1}, fx_n)$  for all  $n$ . From  $fx_0 \neq gx_0$ , it follows that  $d(fx_n, fx_{n+1}) < d(fx_0, gx_0)$  for all  $n$ . Then

$$d(fx_n, fx_0) \leq d(fx_n, gx_n) + d(gx_n, gx_0) + d(gx_0, fx_0)$$

implies

$$d(fx_n, fx_0) - d(gx_n, gx_0) < 2d(fx_0, gx_0).$$

Thus, by (1), we have  $x_n \in M$  for all  $n$ .

If  $x_0 \notin M$ , Theorem 2.4, then the existence of a common fixed point of  $f$  and  $g$  follows immediately by putting  $x = x_0$  in (1). In case  $f = 1_X$ , Theorem 2.4 is due to Rakotch [7, Theorem 1].

Now, following Rakotch [7], we introduce a class of functions.

DEFINITION.  $\mathcal{S}$  is the class of monotonically decreasing functions  $\alpha : (0, \infty) \rightarrow [0, 1)$ .

For  $\alpha \in \mathcal{S}$ , let  $\alpha(x, y) = \alpha(d(fx, fy))$ .

COROLLARY 2.5. A continuous self-map  $f$  of  $X$  has a fixed point iff there exists an  $f$ -contractive map  $g$  in  $C_f$  and a point  $x_0 \in X$  satisfying

$$(2) \quad d(gx, gx_0) \leq \alpha(x, x_0)d(fx, fx_0)$$

for every  $x \in X$ ,  $fx_0 \neq fx$ , where  $\alpha \in \mathcal{S}$  and  $g$  maps the open ball  $B(fx_0, r)$  with  $r = 2d(fx_0, gx_0)/[1 - \alpha(2d(fx_0, gx_0))]$  into a compact subset of  $X$ . Indeed,  $f$  and  $g$  have a unique common fixed point.

PROOF. Suppose that  $f\eta = \eta$  for some  $\eta \in X$ . Defining  $g : X \rightarrow X$  by  $gx = \eta$  and putting  $x_0 = \eta$ , for some constant  $\alpha \in (0, 1)$ , everything is trivially satisfied.

Conversely, in Theorem 2.4, take  $M = B(fx_0, r)$ , then from (2), by the definition of  $\alpha(d)$  and  $r \geq 2d(fx_0, gx_0)$ , it follows that if  $d(fx, fx_0) \geq r$  then

$$\begin{aligned} d(fx, fx_0) - d(gx, gx_0) &\geq d(fx, fx_0) - \alpha(x, x_0)d(fx, fx_0) \\ &= [1 - \alpha(x, x_0)]d(fx, fx_0) \\ &\geq [1 - \alpha(r)]r \\ &> [1 - \alpha(2d(fx_0, gx_0))]r \\ &= 2d(fx_0, gx_0), \end{aligned}$$

that is, (1) holds.

In case  $f = 1_X$ , Corollary 2.5 is due to Rakotch [7].

3.  **$g$ -orbitally complete spaces only.** Given a continuous self-map  $f$  of  $X$ , we introduce a condition on  $X$  somewhat more general than completeness.

DEFINITION. Given  $g \in C_f$ ,  $X$  is said to be  $g$ -orbitally complete w.r.t.  $f$  if, for any  $x \in X$ , every Cauchy subsequence of an arbitrary  $f$ -iteration  $\{f_n\}_{n=1}^\infty$  of  $x$  under  $g$  converges in  $X$ .

The  $g$ -orbital completeness w.r.t.  $1_X$  is just the  $g$ -orbital completeness of Ćirić [3].

For any pair of sequences  $\{x_n\}$  and  $\{y_n\}$  in  $X$  with  $fx_n \neq fy_n$ , we write

$$d_n = d(fx_n, fy_n) \text{ and } \Delta_n = d(gx_n, gy_n)/d_n.$$

We have the following theorem.

**THEOREM 3.1.** *Let  $f$  be a continuous self-map of  $X$  and  $g$  be an  $f$ -contractive map in  $C_f$  such that  $X$  is  $g$ -orbitally complete w.r.t.  $f$ . Let  $x_0 \in X$  and  $\{fx_n\}_{n=1}^\infty$  be an  $f$ -iteration of  $x_0$  under  $g$ . Then  $\{fx_n\}$  converges to a point  $\zeta \in X$  and hence  $f\zeta$  is the unique common fixed point of  $f$  and  $g$  iff, for any two subsequences  $\{fx_{h_n}\}$  and  $\{fx_{k_n}\}$  with  $fx_{h_n} \neq fx_{k_n}$ , we have that  $\Delta_n \rightarrow 1$  implies  $d_n \rightarrow 0$ .*

**PROOF.** Suppose  $fx_n \rightarrow \zeta$  and let  $\{fx_{h_n}\}$  and  $\{fx_{k_n}\}$  be any two subsequences. Then  $d_n = d(fx_{h_n}, fx_{k_n}) \rightarrow 0$  and the condition is satisfied.

Conversely, assume the condition is satisfied for a given point  $x_0 \in X$ . Since  $g$  is  $f$ -contractive, if  $fx_{n+1} = gx_n = fx_n$  for some  $n$ , then  $f$  and  $g$  already have a unique common fixed point by Lemma 2.1. Hence we may assume that  $d(fx_n, fx_{n+1}) = d(gx_{n-1}, gx_n) < d(fx_{n-1}, fx_n)$  for all  $n$ . Now  $d_n = d(fx_n, fx_{n+1})$  is a decreasing sequence of positive numbers and so approaches some  $\epsilon \geq 0$ . Assume  $\epsilon > 0$ . Then letting  $h_n = n$  and  $k_n = n + 1$ , we have  $d_n \rightarrow \epsilon > 0$  while  $\Delta_n \rightarrow 1$ . This leads to a contradiction. Hence  $d(fx_n, fx_{n+1}) \rightarrow 0$ . Now assume that  $\{fx_n\}$  is not Cauchy. Then there exists some  $\epsilon > 0$  such that every tail  $\{fx_n\}_{n \geq N}$  has diameter  $D_N = \sup_{n,m \geq N} d(fx_n, fx_m) > \epsilon$ . Given this  $\epsilon$ , we will construct a pair of subsequences violating the condition. For any  $n > 0$ , let  $N_n$  be so large that  $d(fx_m, fx_{m+1}) < 1/n$  for all  $m \geq N_n$ , as is possible since  $d(fx_m, fx_{m+1}) \rightarrow 0$ . Let  $h_n \geq N_n$  be the smallest integer such that for some  $k_n > h_n$ ,  $d(fx_{h_n}, fx_{k_n}) > \epsilon$ . Such pairs exist by the above diameter condition. Next choose  $k_n$  to be the smallest such integer  $> h_n$ . Then  $d(fx_{h_n}, fx_{k_n-1}) \leq \epsilon$  and  $\epsilon \leq d_n = d(fx_{h_n}, fx_{k_n}) < \epsilon + 1/n$ . Moreover, we have

$$1 \geq \Delta_n = d(gx_{h_n}, gx_{k_n})/d_n \geq (d_n - 2/n)/d_n.$$

So  $\Delta_n \rightarrow 1$  while  $d_n \rightarrow \epsilon > 0$ , again leading to a contradiction. So  $\{fx_n\}$  must be a Cauchy sequence and converges in  $X$  since  $X$  is  $g$ -orbitally complete w.r.t.  $f$ . Now by Theorem 2.2., our proof is complete.

The above proof is essentially that of Theorem 1.1 of Geraghty [5], which is a particular case  $f = 1_X$ . By thoroughly examining the proof, we also obtain the following extended form of Corollary 1.2 of [5].

**COROLLARY 3.2.** *Let  $f$  be a continuous self-map of  $X$  and  $g$  be an  $f$ -contractive map in  $C_f$  such that  $X$  is  $g$ -orbitally complete w.r.t.  $f$ . Let  $x_0 \in X$  and  $\{fx_n\}_{n=1}^\infty$  be an  $f$ -iteration of  $x_0$  under  $g$ . Then  $\{fx_n\}$  converges to a point  $\zeta \in X$ , and hence  $f\zeta$  is the unique common fixed point of  $f$  and  $g$  iff, for any two subsequences  $\{fx_{h_n}\}$  and  $\{fx_{k_n}\}$  with  $fx_{h_n} \neq fx_{k_n}$ , we have that  $\Delta_n \rightarrow 1$ , with  $d_n$  decreasing, implies  $d_n \rightarrow 0$ .*

According to Geraghty [5], we can convert this sequential condition to the more customary functional form.

DEFINITION.  $\mathcal{T}$  is the class of functions  $\alpha : (0, \infty) \rightarrow [0, 1)$  such that

(i)  $\alpha(t_n) \rightarrow 1$  implies  $t_n \rightarrow 0$ . [5]. As before,  $\alpha(x, y) = \alpha(d(fx, fy))$  when  $\alpha \in \mathcal{T}$ .

REMARK. Note that  $\mathcal{S} \subset \mathcal{T}$  and that we do not assume any continuity on  $\alpha$ . Using Corollary 3.2, we can replace (i) by

(ii)  $\alpha(t_n) \rightarrow 1$  with  $t_n$  decreasing implies  $t_n \rightarrow 0$  [5].

Note also that any continuous  $\alpha : (0, \infty) \rightarrow [0, 1)$  is contained in  $\mathcal{T}$  (cf. Corollary 3.8).

THEOREM 3.3. Let  $f$  be a continuous self-map of  $X$  and  $g$  be an  $f$ -contractive map in  $C_f$  such that  $X$  is  $g$ -orbitally complete w.r.t.  $f$ . Let  $x_0 \in X$  and  $\{fx_n\}_{n=1}^\infty$  be an  $f$ -iteration of  $x_0$  under  $g$ . Then  $\{fx_n\}$  converges to some  $\zeta \in X$  and hence  $f\zeta$  is the unique common fixed point of  $f$  and  $g$  iff there exists an  $\alpha$  in  $\mathcal{T}$  such that for all  $n, m, fx_n \neq fx_m$ , we have

$$d(gx_n, gx_m) \leq \alpha(x_n, x_m)d(fx_n, fx_m).$$

PROOF. It suffices to show that the existence of such an  $\alpha$  in  $\mathcal{T}$  is equivalent to the sequential condition of Theorem 3.1. Suppose such an  $\alpha$  exists. Let  $\{fx_{h_n}\}$  and  $\{fx_{k_n}\}$  be subsequences with  $fx_{h_n} \neq fx_{k_n}$ . Assume that  $\Delta_n \rightarrow 1$ . Then it follows from the above inequality that  $\alpha(x_{h_n}, x_{k_n}) \rightarrow 1$ . But then since  $\alpha \in \mathcal{T}$ , we have  $d(fx_{h_n}, fx_{k_n}) \rightarrow 0$ .

Conversely, suppose that the sequential condition holds. Define  $\alpha : (0, \infty) \rightarrow [0, \infty)$  as follows:

$$\alpha(t) = \sup \{d(gx_n, gx_m)/d(fx_n, fx_m) \mid d(fx_n, fx_m) \geq t\}$$

if  $d(fx_n, fx_m) \geq t$  holds for some  $m, n$ ; and  $\alpha(t) = 0$  otherwise. Since  $g$  is  $f$ -contractive, the quotients are all  $< 1$  and so  $\alpha$  is defined for all  $t > 0$  and  $\alpha \leq 1$ . Now assume that  $\alpha(t_n) \rightarrow 1$  for  $t_n \in (0, \infty)$ . We may further assume without loss of generality that  $1 - 1/n < \alpha(t_n) \leq 1$ . Now we have to show  $t_n \rightarrow 0$ . By the definition of  $\alpha(t_n)$ , for each  $n > 0$ , there is a pair  $fx_{h_n}, fx_{k_n}$  in  $\{fx_n\}$  with

$$d(fx_{h_n}, fx_{k_n}) \geq t_n \text{ and}$$

$$1 - 1/n < d(gx_{h_n}, gx_{k_n})/d(fx_{h_n}, fx_{k_n}) \leq \alpha(t_n).$$

So  $\Delta_n \rightarrow 1$ . But then by the sequential condition of Theorem 3.1,  $d(fx_{h_n}, fx_{k_n}) \rightarrow 0$ . So  $t_n \rightarrow 0$ . This completes our proof.

In case  $f = 1_X$ , Theorem 3.3 is reduced to Theorem 1.3 of Geraghty [5].

As consequences of Theorem 3.3 we obtain fixed point theorems.

**THEOREM 3.4.** *A continuous self-map  $f$  of a metric space  $X$  has a fixed point iff there exists an  $f$ -contractive map  $g$  in  $C_f$  such that  $X$  is  $g$ -orbitally complete w.r.t.  $f$ , and there exists a subset  $M \subset X$  and a point  $x_0 \in M$  satisfying the following:*

- (1)  $d(fx, fx_0) - d(gx, gx_0) \geq 2d(fx_0, gx_0)$  for every  $x \in X - M$ ,
- (2)  $d(gx, gy) \leq \alpha(x, y)d(fx, fy)$  for every  $x, y \in M$ ,  $fx \neq fy$ , where  $\alpha \in \mathcal{T}$ . Indeed,  $f$  and  $g$  have a unique common fixed point.

**PROOF.** For the necessity, we just follow the proof of Theorem 2.4 for any constant  $\alpha \in [0, 1)$ . Conversely, if we take an  $f$ -iteration  $\{fx_n\}_{n=1}^\infty$  of  $x_0$  under  $g$ , then we can show that  $x_n \in M$  for all  $n$ , as in the proof of Theorem 2.4. Then the condition of Theorem 3.3 is satisfied.

If  $x_0 \notin M$  in Theorem 3.4, then the existence of a common fixed point of  $f$  and  $g$  follows immediately by putting  $x = x_0$  in (1).

In case  $f = 1_X$ , the above theorem includes Theorem 2 of Rakotch [7]. Note that our proof is simpler.

**THEOREM 3.5.** *A continuous self-map  $f$  of a metric space  $X$  has a fixed point iff there exists an  $f$ -contractive map  $g$  in  $C_f$  and a function  $\alpha$  in  $\mathcal{T}$  such that  $X$  is  $g$ -orbitally complete w.r.t.  $f$ , and*

$$d(gx, gy) \leq \alpha(x, y) d(fx, fy)$$

for all  $x, y \in X$ ,  $fx \neq fy$ . Indeed

- (1)  $f$  and  $g$  have a unique common fixed point  $\eta \in X$ , and
- (2) for any  $x_0 \in X$  and any of its  $f$ -iterations  $\{fx_n\}_{n=1}^\infty$  under  $g$ , we have  $\lim_n g^N fx_n = \eta$ .

**PROOF.** The necessity is clear. For the converse we can apply Theorem 3.3 to any point  $x_0 \in X$ .

In case  $f = 1_X$ , for complete  $X$ , Theorem 3.5 is due to Geraghty [5]. From Lemma 2.1 and Theorem 3.5, we have

**COROLLARY 3.6.** *A continuous self-map  $f$  of  $X$  has a fixed point iff there exists an  $f$ -contractive map  $g$  in  $C_f$  and a function  $\alpha$  in  $\mathcal{T}$  such that, for some integer  $N > 0$ ,  $X$  is  $g^N$ -orbitally complete and*

$$d(g^N x, g^N y) \leq \alpha(x, y) d(fx, fy)$$

for all  $x, y \in X$ ,  $fx \neq fy$ . Indeed,  $f$  and  $g$  have a unique common fixed point.

COROLLARY 3.7. *Let  $f$  be a bijective continuous self-map of a complete metric space  $X$ . If there is an integer  $N > 0$  and a function  $\alpha$  in  $\mathcal{T}$  such that*

$$d(x, y) \leq \alpha(d(f^N x, f^N y))d(f^N x, f^N y)$$

for every  $x, y \in X$ ,  $x \neq y$ , then  $f$  has a unique fixed point.

A few more generalizations of the Banach contraction principle are obtained from the following.

COROLLARY 3.8. *A continuous self-map  $f$  of  $X$  has a fixed point iff there exists an  $f$ -contractive map  $g$  in  $C_f$  such that  $X$  is  $g$ -orbitally complete w.r.t.  $f$  and a function  $\alpha : (0, \infty) \rightarrow [0, 1)$ , which satisfies one of the conditions: (i) monotone decreasing, (ii) monotone increasing, (iii) continuous, and (iv)  $\sup_d \alpha(d) < 1$ , such that*

$$d(gx, gy) \leq \alpha(d(fx, fy))d(fx, fy)$$

for all  $x, y \in X$ ,  $fx \neq fy$ . Indeed,

- (1)  $f$  and  $g$  have a unique common fixed point  $\eta \in X$ , and
- (2) for any  $x_0 \in X$ , any  $f$ -iteration of  $x_0$  under  $g$  converges to some  $\zeta \in X$  satisfying  $f\zeta = g\zeta = \eta$ .

For  $f = 1_X$  and complete  $X$ , Corollary 3.8.(i) is due to Rakotch [7], (iii) to Boyd-Wong [2], and (iv) to many authors. For a complete metric space  $X$  and a constant  $\alpha$ , Corollary 3.8 is due to Jungck [6].

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